

DISTRIBUTION SYSTEM ANALYSIS

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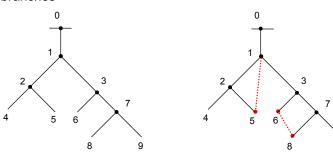
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Outline

- □ Structure of the *Medium Voltage* distribution systems
- ☐ Classification of the *users*
- □ *Model* of the distribution system components
- ☐ Methods of *analysis* of the distribution systems
- ☐ The backward/forward sweep method
- □ Application *examples*

Structure of the distribution systems

- ☐ The Medium Voltage distribution system:
 - · has a weakly meshed structure
 - is operated with radial *configurations* in order to simplify the protection schemes
 - the radial configuration is formed by *opening* the redundant branches



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Radial configuration

- ☐ The choice of the branches to open can be made by using different criteria, the most used are
 - · loss minimisation
 - operation cost minimisation
 - · optimisation of specific reliability indicators
- ☐ Distribution system *supply*:
 - the distribution system can be supplied from multiple points
 - traditionally, the supply points are the HV/MV transformation substations
 - the development of *local* generation systems has increased the number of supply points in the distribution system
 - at the operation level, the system radial configuration concerns the portion of the system supplied by the same HV/MV substation
 - additional sources in the radial configurations make protection schemes and procedures power flow calculation more complicated

Medium Voltage system

☐ Types of *nodes*:

- · supply with protection
- MV/MV substation with disconnects
- loads (MV users and MV/LV substations)

□ Degree of *automation* of the nodes:

- rigid nodes (no accessible switching device)
- remote-controlled nodes (automatic switching from remote centre)
- *locally-controlled* nodes (by local intervention of the operator teams)

☐ System *branches*:

- · overhead or cable lines, transformers
- the branches not connected to supply nodes have no circuit breaker, but only switches at the two sides
- in the MV system with isolated neutral, the switch at the side with the lower degree of automation of each open branch is kept closed in order to simplify the switching operations

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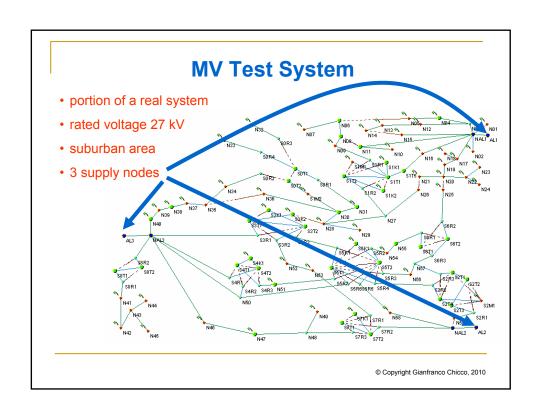
Urban and extraurban MV systems

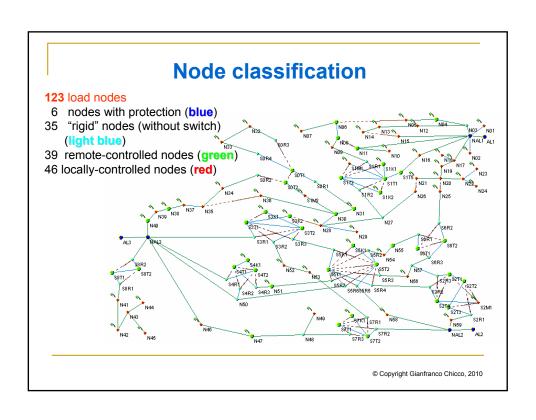
Characteristics:

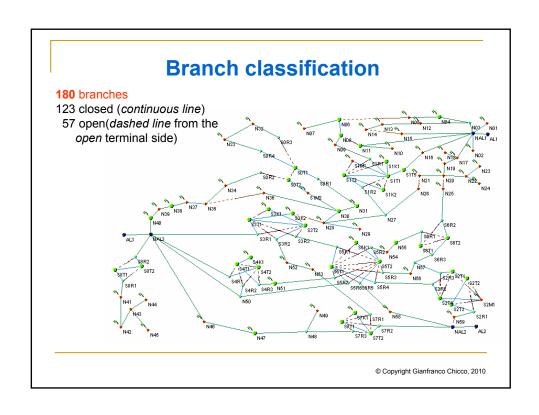
- the *urban* distribution systems are mainly formed by cable lines
- the extraurban distribution systems mainly contain overhead lines
- · load density is a key difference between urban/extraurban systems

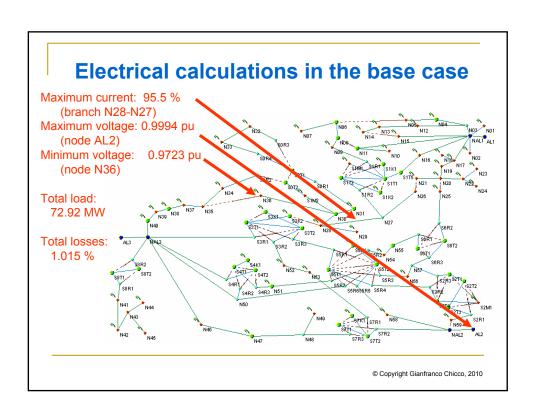
☐ Load density:

- is represented by the *distance of action* of the substations as characteristic parameter
- the *distance of action* indicates the *length* of the lines starting from the substations
- · urban centres: distance of action of about one km
- rural areas: distance of action of one order of magnitude higher
- the choice of the distance of action depends on the trade-off between installation and operation costs
- low distance of action corresponds to a large number of substations installed, but low losses for the single substation (due to the lower line length), and viceversa



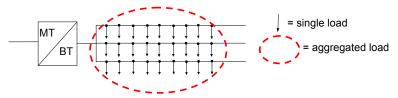






Classification of the users

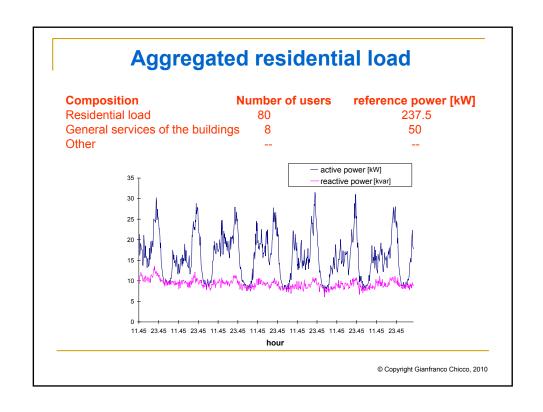
- ☐ Classification based on the *energy use*:
 - · residential users
 - · industrial users
 - users of the *tertiary sector*
 - *other* users (e.g., lighting, traction, etc.)
- □ Each user may exhibit a *variable* load pattern, depending on the type of use of the energy
- ☐ In several cases the distribution system does not supply each residential user individually, but supplies an aggregated load

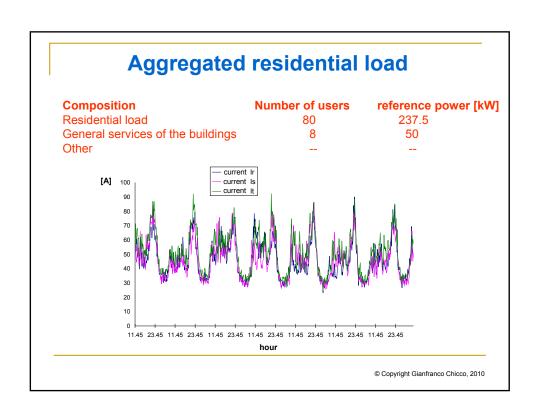


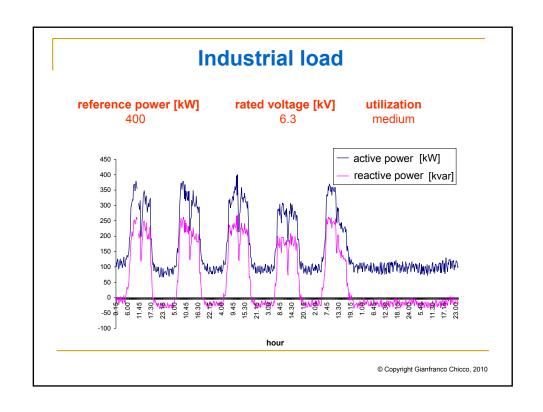
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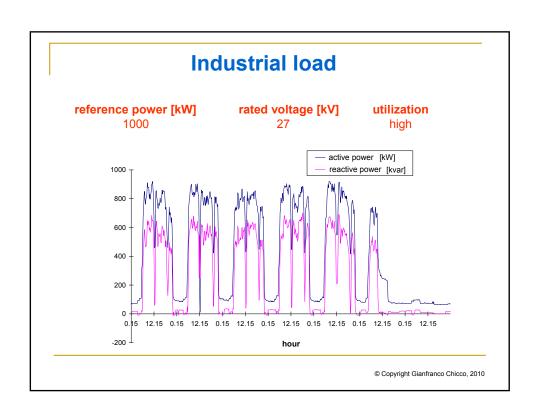
Load aggregation

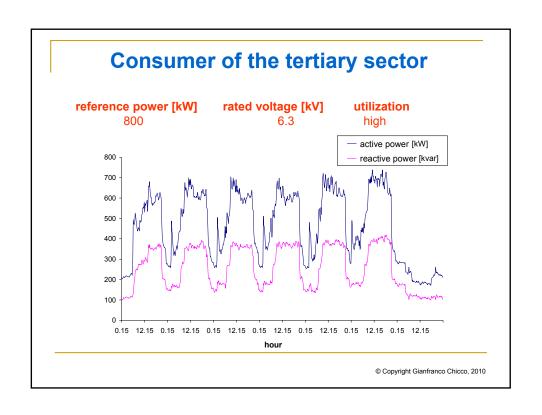
- ☐ For a residential area:
 - the consumption may vary in function of the *number* of persons in the family, of the *activity* of the persons and of their *lifestyle*
 - the characterization of the residential consumption by taking into account the possible load pattern of the electrical appliances would require a statistical analysis based on the various aspects affecting the energy use in the family
 - fortunately, the aggregated load pattern for a significant number of residential customers (e.g., 20-100) connected to the same feeder or substation can be forecast in a relatively easy way
 - the different behavior of the single customers (families) leads to an overall daily evolution of the total load with some regularities
- □ Other users:
 - large industrial and tertiary users are supplied individually
 - It is possible to define the *load patterns* for the single loads

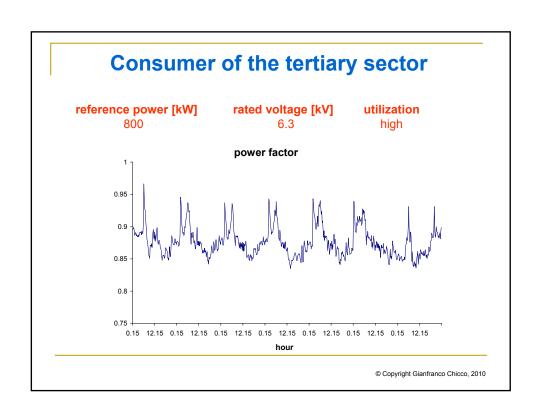


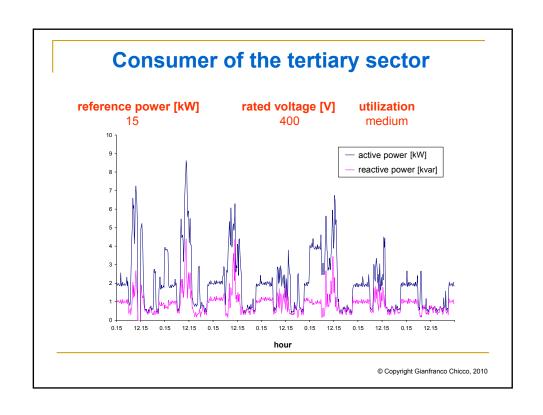


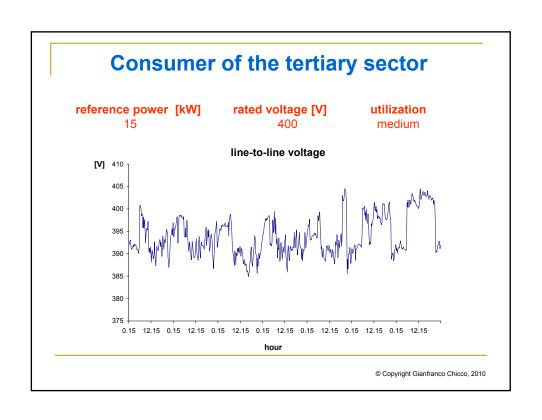












Load patterns ☐ Residential users: · Load pattern with significant portion of base power due to the diversity among the aggregation of similar loads (e.g., refrigerators) although each of them has cycling (intermittent) operation higher consumption during the day (with concentration of the activities) and lower (but non-zero) at night □ Industrial users: · typical patterns with two peaks due to the working activity in the

- morning and in the afternoon and to the lunch pause
 - · energy request reduced during the night

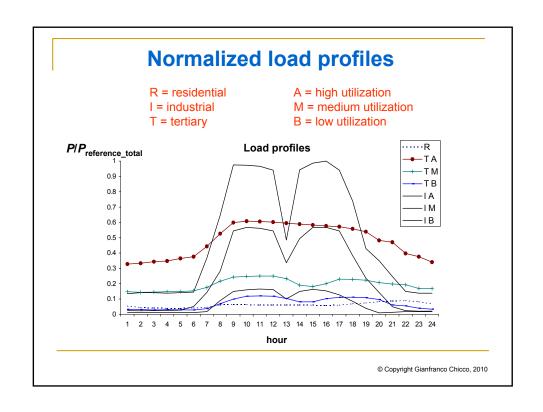
☐ *Tertiary users*:

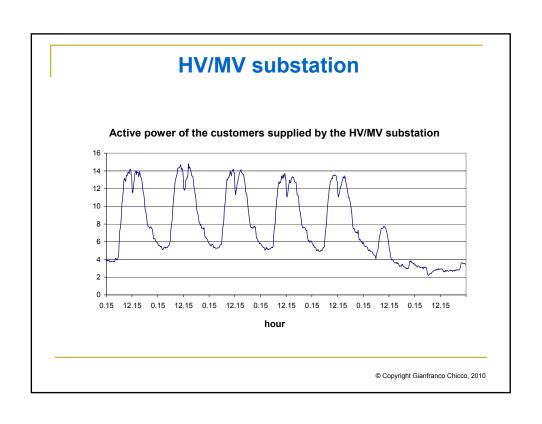
- medium-small users (e.g., small commercial activities and offices): load profile similar to the industrial one
- large users (e.g., shopping malls and large offices): single peak during the day due to continuing working period, and non-negligible demand at night, with services in continuous operation (e.g., refrigerators and lighting)

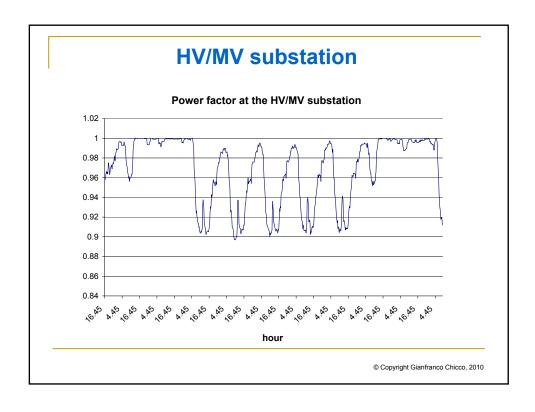
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Load profiles

	duction of the competitive electricity market, the ers may <i>new degrees of freedom</i> to formulate new es
	ge of the <i>electrical load evolution</i> is essential for the ne time-variable tariffs
	analysis carried out on specific load categories, the representative of load aggregations (load profiles) are
	lles are <i>normalized</i> with respect to the peak of the to facilitate their use with different load aggregations
•	iles are used to <i>forecast</i> the evolution of the at the HV/MV or MV/LV substation level
	on allow for identifying <i>criticality</i> and <i>periodicity</i> thly or seasonal) of the consumption oscillations







Objectives of the system analysis

- ☐ The *analysis* of the distribution network requires:
 - the knowledge of the network structure: the topology may vary during the time, with possible branches not used for maintenance or faults, substituted by the redundant branches to maintain the radial configuration
 - the knowledge of the *loads connected*: the loads may be very different among them both for their electrical nature and for their supply parameters
 - "know" the loads means the availability of the evolution of the active and reactive power for all the aggregated users supplied by the network under analysis
 - often the power factor is assumed *constant* and the evolution of the reactive power exchanged is estimated
 - the hypothesis of constant power factor is often plausible: below a certain limit the payment of *extra fees* is required
 - the users apply load *compensation*, so that the power factor may be reasonably (under-)estimated by the value $\cos \varphi = 0.9$

Network analysis

□ Determination of:

- · voltages at every node
- line currents in every branch
- · losses in every branch
- check of the constraints imposed to the system (e.g., losses and currents not higher than a given threshold value, voltages belonging to the admissible interval of values, etc...)
- □ Various *software* tools are used to calculate, at a given instant, all the electrical quantities of interest and to check the constraint satisfaction
- □ If the constraints are not respected, the *control variables* (HV-side supply voltage, transformation ratio variable under load of the HV/MV transformers, possible node capacitors) or the *structure* of the network are modified, opening some branches and closing other branches to restore the radial configuration for all the supply paths to the load nodes

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Model of the components

☐ Generators:

- represented in the HV supply nodes (with explicit model of the HV/MV transformer) or at the MV side (without explicit model of the HV/MV transformer), or modeling local generators
- with more HV/MV substations, each network is analyzed separately
- with a single radial network the generator (0) maintains the voltage constant in amplitude, and serves as phase angle reference
- the corresponding voltage is $\underline{V}_0 = V_0 e^{j0}$

☐ Electrical lines and transformers:

- electric lines are represented by the π equivalent circuit with lumped parameters (RX_L series parameters, and shunt parameters composed of the capacitive susceptance B_C)
- transformers of the HV/MV substations and transformers associated to local generators are represented with the double bipole classical model, with series and shunt parameters
- MV/LV substation transformers typically are not included in the model

Steady-state load models

- Different models for steady-state studies are possible according to the type of load to represent
- Let's consider the subscript 0 to indicate rated or reference conditions
- The common ZIP load representation contains three types of load models:
 - a) assigned *impedance* (modulus $Z = Z_0$ and assigned power factor)
 - b) assigned *current* (amplitude $I = I_0$ and assigned *power factor*)
 - c) assigned power $(P = P_0, Q = Q_0)$
- A more general representation depending on user-defined exponents is

$$P = P_0 (V/V_0)^{\alpha} \qquad Q = Q_0 (V/V_0)^{\beta}$$

and varying the exponents α and β it is possible to obtain the previous models:

 $\alpha = \beta = 2 \rightarrow \text{back to the model a}$

 $\alpha = \beta = 1 \rightarrow \text{back to the model b}$

 $\alpha = \beta = 0 \rightarrow \text{back to the model c}$

or hybrid models (e.g., $\alpha = \beta = 1.5$, cases with $\alpha \neq \beta$, or even negative exponents)

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Steady-state load models

- The above indicated models can be combined into polynomial forms
- The load dependence on the system frequency can be represented explicitly, multiplying the load by a factor $(1 + \gamma (f f_0))$, where f is the actual frequency, f_0 is the rated frequency and γ is the load sensitivity to the system frequency
- The EPRI LOADSYN model is a widely used model that summarizes the characteristics of the previously indicated formulations
- The active power load is divided into two fractions: the fraction P_{a1} depends on frequency with sensitivity KPF1 and on voltage (exponent KPV1); the complementary fraction depends on voltage (exponent KPV2)
- The reactive power load, having initial reactive power Q' without compensation, is divided into two terms: one (with parameters $Q_{a1} = Q'/P_0$, KQF1 and KQV1) refers to all load components, the other (with parameters KQF2 and KQV2) approximates the effect of reactive "losses" and compensation in the subtransmission and distribution system

EPRI LOADSYN model

Formulation of the EPRI LOADSYN model

$$P = P_0 \left[P_{a1} \left(\frac{V}{V_0} \right)^{KPVI} \left(1 + KPFI (f - f_0) \right) + \left(1 - P_{a1} \left(\frac{V}{V_0} \right)^{KPV2} \right) \right]$$

frequency-dependent load models

frequency-independent load models

$$Q = Q_0 \left[Q_{a1} \left(\frac{V}{V_0} \right)^{KQVI} \left(1 + KQFI (f - f_0) \right) + \left(\frac{Q_0}{P_0} - Q_{a1} \right) \left(\frac{V}{V_0} \right)^{KQV2} \left(1 + KQF2 (f - f_0) \right) \right] \right]$$

reactive power of all load components

effect of reactive "losses" and compensation in the networks

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Uniformly distributed load

 \square Representation of a feeder of length ℓ and total current I_T with similar loads ☐ Hypotheses:

n loads, $dx = \ell/n$, $di = I_T/n$ impedance $Z = z \ell$

equal power factor for each current

- ☐ Searching for an *equivalent lumped load* representation: at what distance has the equivalent load to be introduced?
 - a) criterion of maintaining the same *voltage drop* $\Delta V \approx \text{Re}\{\overline{Z}\ \overline{I}\}\$
 - first segment $\Delta V_1 = \text{Re}\{z \, dx \, n \, di\}$
 - second segment $\Delta V_2 = \text{Re}\{z \, dx \, (n-1) \, di\}$
 - total voltage drop $\Delta V_{TOT} = \text{Re}\{z \, dx \, di [n + (n-1) + ... + 1]\}$

Since 1 + 2 + 3 + ... + n = n(n+1)/2

$$\Delta V_{ror} = \text{Re}\left\{z \, dx \, di \, n(n+1)/2\right\} = \text{Re}\left\{\frac{1}{2} Z \, I_r \left(1 + \frac{1}{n}\right)\right\}$$

for $n \to \infty$: $\Delta V_{ror} = \text{Re}\left\{\frac{1}{2}ZI_r\right\}$ alternatives *l*/2

Uniformly distributed load

- b) criterion of maintaining the same total branch losses
- $\Delta P_1 = 3 r \, dx |n \, di|^2$ first segment
- second segment $\Delta P_2 = 3 r dx |(n-1)di|^2$
- $\Delta P_{TOT} = 3 r dx |di|^2 \left[n^2 + (n-1)^2 + ... + 1^2 \right]$ total losses Since $1^2 + 2^2 + 3^2 + ... + n^2 = n(n+1)(2n+1)/6$

$$\Delta P_{TOT} = 3 r \frac{\ell}{n} \left| \frac{I_{\tau}}{n} \right|^{2} \left(\frac{n(n+1(2n+1))}{6} \right) = 3 R |I_{\tau}|^{2} \left[\frac{1}{3} + \frac{1}{2n} + \frac{1}{6n^{2}} \right]$$

for
$$n \to \infty$$
: $\Delta P_{rot} = 3\frac{R}{3}|I_r|^2$

The equivalent representations for maintaining the same voltage drop or the same total branch losses are different!

It is not possible to use a lumped representation with a single load

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Uniformly distributed load

☐ The exact model working for all cases has two lumped loads, such that

$$\stackrel{I_T}{\longrightarrow} \stackrel{k \ell \quad (1-k) \ell}{\longrightarrow} \stackrel{(1-c) I_T}{\longrightarrow} c I_T$$

The coefficients c and k are obtained by considering

$$\Delta V_{ror} = \text{Re}\left\{\frac{1}{2}ZI_{r}\right\} = \text{Re}\left\{kZI_{r} + (1-k)ZcI_{r}\right\} \Longrightarrow \frac{1}{2} = k + (1-k)c \Longrightarrow k = \frac{\frac{1}{2}-c}{1-c}$$

$$\Delta P_{TOT} = 3 \left[\frac{R}{3} |I_{\tau}|^{2} \right] = 3 \left[k R |I_{\tau}|^{2} + (1 - k) R |c I_{\tau}|^{2} \right] \longrightarrow \frac{1}{3} = k + (1 - k) c^{2} = k (1 - c^{2}) + c^{2}$$

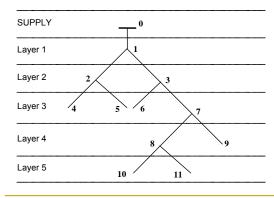
After substituting the expression of *k* into the last equation \implies $c = \frac{1}{3}$

Thus, $k=\frac{1}{4}$ and the final solution for the circuit is $I_{\underline{T}} = \frac{\ell/4}{2} \frac{3\ell/4}{I_{\underline{T}}/3} I_{\underline{T}}/3$

$$\stackrel{I_{T_{+}}}{\xrightarrow{\qquad}} \stackrel{\ell/4}{\xrightarrow{\qquad}} \stackrel{3\ell/4}{\xrightarrow{\qquad}} \stackrel{I_{T/3}}{\xrightarrow{\qquad}} \stackrel{I_{T/3}}{\xrightarrow{\qquad}}$$

Distribution system structure

- The electricity distribution system structure can be considered as stratified into layers to simplify its numerical treatment
- The layer representation of the distribution system structure includes the nodeto branch incidence matrix (L) and its inverse (Γ)
- Both matrices can be built by visual inspection



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Distribution system representation

- Other relevant matrices and vectors are
 - \Box the (diagonal) matrix \mathbf{Z}_B containing the branch impedances
 - $_{ extstyle e$

$$\mathbf{i}_{S} = \underbrace{\frac{I_{S1}}{I_{S2}}}_{I_{S3}}$$

$$\mathbf{i}_{S} = \underbrace{I_{S5}}_{I_{S6}}$$

$$\underbrace{I_{S6}}_{I_{S7}}$$
...

Distribution system load flow

- single-phase equivalent load flow (for balanced three-phase systems)
- three-phase load flow (for unbalanced systems)
- probabilistic load flow (with uncertain data)
- harmonic load flow (with distorted waveforms)

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Load flow for balanced systems

- Generally, the *currents* contained in the vector i_S depend on the value of the node *voltage*, e.g.:
 - □ for a load with specified *impedance* \underline{Z}_{Ci} at node i (e.g., power factor correction capacitor, or representation of the shunt branch parameters), the current is $\underline{I}_{Si} = \underline{V}/\underline{Z}_{Ci}$
 - □ for a load with specified power $\underline{S}_{Ci} = P_{Ci} + j \ Q_{Ci}$ at node i, the current is $\underline{I}_{Si} = \underline{S}_{Ci}^* / \underline{V}_i^*$
- The initial values of the complex node voltages are fixed at each node i = 1,..., n, e.g., with values equal to the voltage at the supply node

$$\underline{V}_{i}^{(0)} = \underline{V}_{0} = V_{0} e^{j0}$$

Backward/forward sweep method

- The load flow calculation is carried out by using an iterative procedure called Backward/Forward Sweep (BFS)
- The *k*-th iteration is composed of *two stages*
 - Backward stage: given the load data and complex voltages at the load terminals, compute the complex branch currents, starting from the load terminals and moving "backward" to the root
 - Forward stage: given the branch currents, compute the complex voltages at the load terminals, proceeding "forward" from the root to the load terminals
- The two stages are repeated iteratively, until the difference between the load voltages computed at the current iteration and at the previous iteration becomes lower than a specified *tolerance*, thus leading to convergence

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Backward stage

- At the iteration k, the components of the node current vector $\mathbf{i}_{S}^{(k)}$ are
 - □ For the impedance-specified load at node *i*, with impedance \underline{Z}_{Ci}

$$\underline{I}_{Si}^{(k)} = \underline{V}_{i}^{(k-1)} / \underline{Z}_{Ci}$$

□ For the power-specified load at node h, with complex power \underline{S}^*_{Ch}

$$\underline{I}_{Sh}^{(k)} = \underline{S}^*_{Ch} / \underline{V}^*_{h}^{(k-1)}$$

■ The branch current vector i_B is then computed as

$$\mathbf{i}_{B}^{(k)} = \Gamma^{\mathsf{T}} \; \mathbf{i}_{S}^{(k)}$$

Forward stage

At the iteration k, the node voltages are computed starting from the voltage V₀ at the root node by using the relationship

$$\mathbf{v}^{(k)} = V_0 \mathbf{1} - \Gamma \mathbf{Z}_{\mathsf{B}} \mathbf{i}_{\mathsf{B}}^{(k)}$$

- where
 - □ 1 is a column vector with all unity components
 - the matrix Γ practically represents a "filter" applied to the matrix \mathbf{Z}_{B} to consider, for each node, only the impedances located in the path from that node and the root
 - the vector $\Gamma \mathbf{Z}_{B} \mathbf{i}_{B}^{(k)}$ gives for each node the *voltage drop* occurring from the root node to the specified node

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Stop criterion

For each node, the following difference is considered between the voltage computed at the current iteration and the voltage at the previous iteration:

$$\max_{i} \left\{ \frac{\left| \underline{V}_{i}^{(k+1)} - \underline{V}_{i}^{(k)} \right|}{V_{i}^{(k)}} \right\} < \varepsilon \qquad \text{for } i = 1, ..., n$$

The iterative process *terminates* when the maximum relative error (for the node in which the error is maximum) is lower than the specified threshold ε , otherwise the iterations continue

BFS as a Gauss method

 The two stages of the backward/forward sweep method can be merged to obtain the formulation

$$\mathbf{v}^{(k)} = \mathbf{V}_0 \mathbf{1} - \Gamma \mathbf{Z}_{\mathrm{B}} \Gamma^{\mathrm{T}} \mathbf{i}_{\mathrm{S}}^{(k)}$$

 Every node current is a function of the corresponding node voltage computed at the previous iteration

$$\mathbf{i}_{\mathrm{S}}^{(k)} = g(\mathbf{v}^{(k-1)})$$

 The BFS method can then be seen as a Gauss-type numerical method, where

$$\mathbf{v}^{(k)} = f(\mathbf{v}^{(k-1)})$$